# Toward a modeling theory of physics instruction <sup>a)</sup>

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An analysis of the conceptual structure of physics identifies essential factual and procedural knowledge which is not explicitly formulated and taught in physics courses. It leads to the conclusion that mathematical modeling of the physical world should be the central theme of physics instruction. There are reasons to believe that traditional methods for teaching physics are inefficient and substantial improvements in instruction can be achieved by a vigorous program of pedagogical research and development.

#### I. WHO NEEDS A THEORY OF INSTRUCTION?

The generally unsatisfactory outcome of instruction in introductory physics is too familiar to require documentation. Blame is usually placed on poor prior training in mathematics and science. However, cognitive research in the last decade has documented serious deficiencies in traditional physics instruction. There is reason to doubt that these deficiencies can be eliminated without extensive pedagogical research and development.

Pedagogical theory is generally held in low esteem by university scientists. But their own practices show how sorely it is needed. They practice in the classroom what they would never tolerate in the laboratory. In the laboratory they are keen to understand the phenomena and critically evaluate reasonable alternative hypotheses. But their teaching is guided by unsubstantiated beliefs about students and learning which are often wrong or partial truths at best. This kind of behavior would be as disastrous in the laboratory as it is in the classroom. Why don't they evaluate their teaching practices with the same critical standards they apply to scientific research?

Although deficiencies in physics instruction are most serious at the introductory level, there is no reason to believe that they are insignificant at higher levels. To be sure, some excellent physicists emerge from our graduate programs. But symptoms of a problem are easy to find in the frequent jokes and lamentations by faculty over the poor performance of graduate students, especially on oral exams where students are supposed to demonstrate a coherent understanding of their subject. The possibility that this might be a consequence of deficient instruction seems never to occur to the faculty. In the absence of evidence you can believe what you like. The fact that, with sufficient time and effort, some students learn physics in our universities should not make us complacent. The question is not whether students can learn physics, but whether instruction can be designed to help them learn it more efficiently.

Most physics professors take their teaching seriously, so it seems strange that they have not promoted the kind of coherent research program to improve teaching which they know is essential to the development of physics. My purpose in this article is to discuss what is needed to get such a program started. I aim to formulate the rudiments of an instructional theory in sufficient detail to serve as a

basis for criticizing current instructional practice and guiding pedagogical research. And I hope to call attention to related research in cognitive science which can be expected to contribute to the development of instructional theory. The ultimate goal of pedagogical research should be to establish a mature instructional theory which consolidates and organizes a nontrivial body of knowledge about teaching. Without such a theory, little pedagogical knowledge can be transmitted between generations of teachers, teachers cannot improve without repeating mistakes of their predecessors, and only the most capable and dedicated can progress to teaching with a moderate degree of insight and subtlety. Such is the situation today. Without the consolidation of physical knowledge in theory, could we expect any physicists to develop beyond the insights of Galileo? A theory of instruction must answer two questions: "What are the essentials of the subject to be taught?" and "How can the essentials be taught effectively?" Section II of this article offers an answer to the first question from an analysis of the structure of scientific knowledge. A specific theory of mathematical models and modeling is outlined for pedagogical purposes. This provides the basis for a model-centered instructional strategy, which is the heart of the instructional theory.

For the most part, the *modeling theory* should appear obvious to physicists, since it is supposed to provide an explicit formulation of things they know very well. That does not mean that the theory is trivial or unnecessary. Much of the knowledge it explicates is so basic and well known to physicists that they take it for granted and fail to realize that it should be taught to students. A systematic explication of basic knowledge is an obvious prerequisite to the development of an instructional program which assures that the basics are adequately taught. When an instructor takes certain basics for granted and fails to teach them, the students flounder until they rediscover those basics for themselves or, more likely, develop inferior alternatives to cope with their difficulties. I submit that this unfortunate state of affairs is rampant in physics courses and contributes heavily to their legendary difficulty.

At the risk of purveying jargon, I have introduced some new terminology to designate important concepts in instructional science. Hopefully, this will contribute to further sharpening and exploitation of these concepts in the future. Like any other science, instructional science needs to develop its own specialized vocabulary and conceptual structure.

As a nontrivial application of the theory, I use it for a systematic explication of basic knowledge which should be taught in introductory mechanics. This leads to specific criticisms of current teaching practice. My intent is not to condemn, but to ascertain how teaching can be improved. If I seem to be articulating the obvious, let it be noted how haphazardly basic knowledge is taught in physics courses. If my analysis is defective, let that be a point of departure for improving the theory.

While Sec. II offers an answer to the question about what should be taught, a satisfactory answer to the question about how it can be taught effectively is not to be expected without extensive pedagogical research. To help guide and stimulate the necessary research, Sec. III is devoted to delineating some of the issues and reviewing relevant facts and ideas from cognitive science and other sources.

# **II. THE STRUCTURE OF SCIENTIFIC KNOWLEDGE**

Scientific knowledge is of two kinds, factual and procedural. The factual knowledge consists of theories, models, and empirical data interpreted (to some degree) by models in accordance with theory. A theory is to be regarded as factual, rather than hypothetical, because the laws of the theory have been corroborated, though theories differ in range of application and degree of corroboration. The procedural knowledge of science consists of strategies, tactics, and techniques for developing, validating, and utilizing factual knowledge. This rather vague and disorganized system, or some part of it, is commonly referred to as the scientific method.

Factual knowledge is presented in science textbooks in a fairly explicit and orderly fashion, though rather haphazardly, with frequent logical gaps and hidden assumptions. However, the usual textbook treatment of procedural knowledge is almost totally inadequate, consisting of little more than platitudes about the power of scientific method and off-hand remarks about problem solving. Students are left to discover essential procedural knowledge for themselves by struggling with practice problems and observing the performance of professors and teaching assistants. This is as difficult for students as it has been for the philosophers, who have failed to give an adequate account of scientific method. No wonder that so many students fail in this endeavor. But the fact that so many succeed testifies to the widespread creative powers of the human intellect.

To teach procedural knowledge efficiently, we need a theory to organize it. This will depend on how we characterize the structure of factual knowledge. Scientists generally agree that such structure is supplied by models and theories, but satisfactory definitions of the terms "model" and "theory" are not to be found in standard physics textbooks, and few scientists could supply them. For most scientists their meanings are derived from familiarity with a large collection of examples. But we can hardly hope to impart clear concepts of "model" and "theory" to students, who lack the background of scientists, unless we can characterize these concepts explicitly. Our first task in this section will be to supply such a characterization. The results will help us identify logical gaps and tacit assumptions in conventional textbooks which surely leave students confused. More important, we shall see that the concept of theory presupposes the concept of model. This leads us to the identification of model development and deployment as the main activities of scientists, and thus provides the key to a coherent theory of procedural knowledge in science.

The second task in this section will be to explicate the principles and techniques of modeling for pedagogical purposes. I will be specifically concerned with applications to the teaching of introductory mechanics, since that is where physics instruction usually begins. But I aim to formulate general modeling principles applicable to every branch of physics, indeed, to every branch of science.

Our discussion of models, theories and modeling in this section hits only the highlights of greatest pedagogical interest. A more detailed discussion is given in Ref. 1, from which the main ideas in this section were taken. A valuable analysis of knowledge structure in mechanics from a closely related point of view is given by Reif and Heller.<sup>2</sup>

# A. Model

A model is a surrogate object, a conceptual representation of a real thing. The models in physics are mathematical models, which is to say that physical properties are represented by quantitative variables in the models.

A mathematical model has four components:

- (1) A set of *names* for the object and *agents* that interact with it, as well as for any part of the object represented in the model.
- (2) A set of *descriptive variables* (or *descriptors*) representing properties of the object.
- (3) *Equations of the model*, describing its structure and time evolution.
- (4) An *interpretation* relating the descriptive variables to properties of some object which the model represents.

There are *three types of descriptors:* object variables, state variables, and interaction variables.

*Object variables* represent intrinsic properties of the object. For example, mass and charge are object variables for an electron, while moment of inertia and specifications of size and shape are object variables for a rigid body. The object variables have fixed values for a particular object, so they are indeed variables from the viewpoint of modeling theory.

*State variables* represent intrinsic properties with values which may vary with time. For example, position and velocity are state variables for a particle. A descriptor regarded as a state variable in one model may be regarded as an object variable in another model. Mass, for example, is a state variable in a particle model of a rocket, though it is constant in most particle models. Thus, object variables can be regarded as state variables with constant values.

An *interaction variable* represents the interaction of some external object (called an agent) with the object being modeled. The basic interaction variable in mechanics is the force vector. Work, potential energy, and torque are alternative interaction variables.

In particle mechanics, the equations of a model typically consist of *equations of motion (dynamical equations)* for each particle in the model and possibly *equations of constraint* describing certain kinds of interaction. For some purposes it is convenient to replace the equations of motion by conservation laws relating state variables at different times. This gives an alternative representation of the object, but it is not a different model unless the specified conservation laws contain less information than the equations of motion, as is sometimes the case. In the equations of a model the "internal interaction variables," describing interactions among parts of a composite object, are expressed as functions of the state variables, so they are dependent variables which can be eliminated mathematically. Nevertheless, they are essential to the interpretation of the model.

Interpretations are treated so casually in physics textbooks that one should not be surprised to find them muddled by students. Indeed, a common practice among physicists and mathematicians is to identify the equations of a model with the model itself. This, of course, takes the interpretation of the model for granted, which may be okay for experienced scientists, though the interpretation is not infrequently a serious bone of contention. But students need to recognize the interpretation as a critical component of a model. Without an interpretation the equations of a model represent nothing; they are merely abstract relations among mathematical variables. Undoubtedly, this is how the equations often appear to confused physics students, who have not developed the ability of the instructor to supply an interpretation automatically.

### **B.** Theory

A scientific theory can be regarded as a system of design principles for modeling real objects. This viewpoint makes it clear that the concept of theory presupposes the concept of model. Indeed, a scientific theory can be related to experience only by using it to construct specific models which can be compared with real objects. The laws of a theory can be tested and validated only by testing and validating models derived from the theory.

A *scientific theory* has three major components:

- (I) *A framework* of generic and specific laws characterizing the descriptive variables of the theory.
- (II) A *semantic base* of correspondence rules relating the descriptive variables to properties of real objects.
- (III) A *superstructure* of definitions, conventions and theorems to facilitate modeling in a variety of situations.

The framework determines the structure of the theory, while the semantic base determines the interpretation of the theory and any models derived from it. The framework and semantic base are essential components of the theory, and any significant change in them produces a new theory. However, the superstructure is subsidiary, growing and changing with new applications of the theory.

'the concept of a scientific law is widely recognized as the key concept in a scientific theory, yet textbooks rarely attempt to define it, or even distinguish clearly between the different types of law. A scientific law is a relation among descriptive variables which is presumed to represent a relation among properties of real objects, because it has been validated in some empirical domain by the testing of models. Most of the laws of physics are expressed as mathematical equations. The laws of a theory are either basic or derived. The basic laws, such as Newton's laws of motion, are independent assumptions in the framework of the theory. The derived laws, such as the Work-Energy Theorem and Galileo's law of falling bodies, are theorems in the superstructure of the theory.

Generic laws define the *basic descriptive variables* of the theory. Generic laws apply to every model derived from the theory, whereas specific laws apply only under special conditions. Newton's three laws of motion are generic laws of classical mechanics defining the basic variables mass and force. Unfortunately, textbooks give the false impression that these are the only generic laws of mechanics, and they fail to point out that Newton's formulation is insufficient to define the concept of force completely. A complete formulation and analysis of the generic laws of mechanics is given in Ref. 1. I will not go into such detail here, because beginning students are not equipped to appreciate it. However, a thorough analysis helps identify serious deficiencies in the conventional formulation which are likely to cause students difficulty.

Newton's laws are often paraphrased in the textbooks to make them more intelligible to students, but the deficiencies in Newton's original formulation are retained. First, the laws fail to explicitly state that *every force has an agent*, that every force is a binary function describing the action of an agent on an object. The seriousness of this deficiency is shown by empirical evidence<sup>3,4</sup> that the majority

of students hold the "impetus belief" that a force can be imparted to an object and act on it independently of any agent; moreover, few students change this belief after instruction in mechanics. Second, Newton's formulation speaks of the force on a body rather than a particle. A rigorous formulation begins with forces on and by particles and later defines the force on a body as the sum of forces on its particles. Most textbooks do not make it clear that Newton's second law cannot be applied directly to a body unless the body is modeled as a particle. This blurs the distinction between Newton's second law and the center of mass theorem. Surely, the blurred distinction between body and particle contributes to the difficulties students have in identifying the location of forces acting on an extended body. A third deficiency is Newton's failure to state the force superposition principle as a separate law, because he mistakenly believed it could be derived from his other laws. The superposition principle is sometimes stated as part of the second law, but it is so important it deserves separate billing. There are more subtle difficulties with the formulation of Newton's laws which I need not go into here, because they are of lesser pedagogical interest.

Besides deficiencies in the formulation of Newton's Laws, the whole set of laws is incomplete in two important respects: First, the *basic kinematical laws* defining the concepts of position, time and motion are not explicitly formulated. Second, the logical status of specific force laws, like Newton's law of gravitation, is not sharply delineated. Students are not informed that the *concept of a force law is an essential part of the concept of a force.* Incompleteness in the formulation of the basic laws of mechanics is a matter of pedagogical concern. For how are students to distinguish basic concepts and laws from derived concepts and laws? How are they to distinguish the essential from the peripheral? How are they to identify discrepancies between their own beliefs and scientific concepts if the latter are not sharply delineated?

Instead of merely listing Newton's laws, as is usually done, it would be better to classify the laws according to their roles in the theory. *The laws of mechanics are of three types:* kinematical, dynamical, and interaction laws. This classification applies to basic as well as derived laws. And it has the added advantage of wide applicability outside of mechanics. Awareness of the classification should help guide the students in applying the laws.

The basic kinematical laws define the concepts of physical space, time, reference frame, particle, position, and trajectory. Newton's first law belongs to this class, because it defines inertial frames by distinguishing them from accelerated reference frames. Aside from this law, textbooks introduce the other kinematical laws informally and unsystematically without identifying the laws. It is all very well to teach kinematics informally, but students need help to distinguish between physical laws and mere mathematical formulas. Why not let them know that the familiar Pythagorean Theorem applied to physical space is a physical law, because it specifies a relation between independent measurements of length? This prepares them for the idea of curved space in Einstein's general theory. Why don't the textbooks identify the velocity addition theorem (relating velocities in different reference systems) as a derived kinematical law? That would prepare students for the eventual realization that the law is only approximately true according to Einstein's special theory. Without formulating the basic kinematical laws of classical physics explicitly, how are students to appreciate that Einstein's special and general theories of relativity are both modifications of those laws? If this is deemed to be too esoteric for an

introductory physics class, let it be asked, "To what degree is the confusion of students on relations between physical descriptions in different reference systems the result of insufficient specifications of the physical laws involved?"

Dynamical laws determine the time evolution of state variables in models. The basic dynamical law of mechanics is, of course, Newton's second law. But there are many other derived dynamical laws that apply under special conditions, e.g., the laws of energy, momentum and angular momentum conservation. Other dynamical laws apply to special model types. For example, two dynamical laws are needed to characterize rigid body motion: the center-of-mass theorem to characterize translational motion, and the torque-angular momentum theorem to characterize rotational motion.

The basic interaction laws of Newtonian mechanics include Newton's third law and the force superposition law as well as a variety of specific force laws, such as Newton's law of gravitation. Conservative interactions can alternatively be characterized by potential energy functions. Sometimes interactions are expressed by equations of constraint. Students could benefit from a complete and systematic classification and description of interactions and interaction laws, with emphasis on the agents for each interaction type and conditions under which the interactions are significant. Research<sup>3,4</sup> shows that, under conventional instruction, students are slow to master interaction concepts, perhaps because they are not clear about what to master.

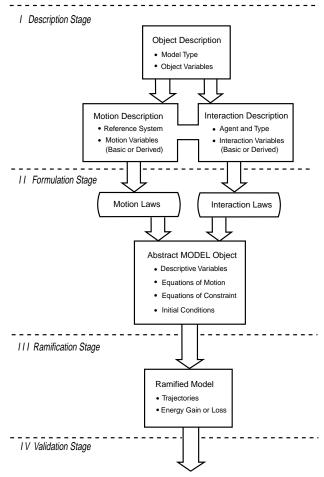


Fig. 1. Model development in mechanics.

## C. Modeling and problem solving

The cognitive process of applying the design principles of a theory to produce a model of some physical object or process is called *model development* or simply *modeling*. A strategy for model development in mechanics is outlined schematically in Fig. 1. The strategy coordinates the application of scientific and mathematical knowledge to the modeling of physical objects and processes. It subdivides the model development process into four major stages to be implemented successively, as indicated by the arrows on the substages in Fig. 1. The implementation of each substage is directed by special modeling tactics for the particular kind of model being developed.

The modeling strategy outlined in Fig. 1 is obvious to physicists, since they have learned to follow it automatically in the analysis of physical situations and problems. Indeed, Fig. 1 may be regarded as an outline of *essential* steps in the modeling process instead of a prescribed strategy. However, since each step is essential to modeling, the prescribed strategy must be followed, though there is some leeway in the order in which the steps are taken and back-tracking is often necessary. The physicist has learned the modeling strategy from long experience, and beginning physics students will flounder until they learn it themselves. The teaching of explicitly formulated modeling strategies and tactics should accelerate the learning of effective modeling skills.

I submit that problem solving in physics is primarily a modeling process. Accordingly, I propose the modeling strategy of Fig. 1 as a general problem solving strategy to be taught explicitly to physics students. To understand how the strategy applies, we need to see how it coordinates specific modeling tactics and techniques. With that objective, let us discuss the four stages of modeling—(I) *Description*, (II) *Formulation*, (III) *Ramification*, and (IV) *Validation—in* the order of their implementation.

(I) *The Description Stage* is severely constrained by our choice of mechanics as the theory to be applied, for the theory specifies what kind of objects and properties can be modeled. Note that the three components of the descriptive stage correspond to the three types of descriptive variables. The main output of the descriptive state is a complete set of names and descriptive variables for the model, along with physical interpretations for all the variables.

The object description requires a decision as to the type of model to be developed. For example, a given solid object could be modeled as a *material particle*, a *rigid body*, or an *elastic solid*. The theory provides special modeling principles and techniques for each different model type.

In a motion description (Fig. 1) the state variables of the model are specified. The state variables may be either basic or derived. *Basic variables* are defined implicitly by generic laws of the theory, while *derived variables* are defined explicitly in terms of basic variables. In mechanics, particle positions and velocities are the basic state variables, while center-of-mass position, kinetic energy, momentum, and angular momentum are derived variables. To determine the optimal choice of state variables is a tactical problem whose solution depends on the type of process being modeled. For example, position and velocity variables are usually best for projectile motion, while momentum and kinetic energy are usually best for collisions. Note that the state variables are not welldefined without (tacitly, at least) invoking kinematical laws and specifying a reference frame. Besides specifying the state variables, a motion description characterizes the motion as a whole, at least qualitatively, and specifies any known values of the state variables. A variety of modeling techniques have been developed for this purpose, including tables, maps, and graphs. For pedagogical purposes, motion maps, such as those in Fig. 2, deserve special emphasis. A *motion map* for a

Kinematical Type	Defining equations		Solution		Motion Map	
	vectorial	coordinate	vectorial	coordinate		
Uniform Velocity	$\mathbf{v} = \mathbf{v}_0$ $(\mathbf{a} = 0)$	$v = v_0$ $(a = 0)$	$\mathbf{r} = \mathbf{r}_0 + \mathbf{v}t$	$x = x_0 + vt$	x <sub>0</sub>	x x-axis
1-dim Uniform	$\mathbf{a} = \mathbf{a}_0$ $\mathbf{a} \times \mathbf{v} = 0$	$a_x = a_{0x}$ = $a$	$\mathbf{v} = \mathbf{v}_0 + \mathbf{a}t$	$v = v_0 + at$ $x = x_0 + \frac{1}{2}at^2 + vt_0$ $v^2 = v_0^2 + 2a(x - x_0)$	$a$ $a$ $v_0$ $v$ $v$ $a$ $a$ $v_0$ $v$ $v$	
Acceleration 2Đdim	$\mathbf{a} = \mathbf{a}_0$ $\mathbf{a} \ge \mathbf{v} \neq 0$	$a_y = a_{0y}$ $= a$ $a_x = 0$ $v_x \neq 0$	$\Delta \mathbf{r} = \mathbf{v}_0 t + \frac{1}{2} \mathbf{a} t^2$ $\mathbf{v}^2 = \mathbf{v}_0^2 + 2\mathbf{a} \cdot \Delta \mathbf{r}$ $\Delta \mathbf{r} = \mathbf{r} - \mathbf{r}_0$	$v = v_{0x}$ $x = x_0 + v_{0x} t$ $v_y = v_{0y} + at$ $y = y_0 + v_{0y} t + \frac{1}{2} at^2$ $v_y^2 = v_{0y}^2 + 2a(y - y_0)$	$v_0 / v_{0y}$ $v_{0x}$ $v_0 / a$ $v_0 / a$	a      y      y     v     v     v     v     a     v     a     v     a     v     a     v     a     v     a     v     a     v     a     v     a
Uniform Circular Motion	$\mathbf{a} \cdot \mathbf{v} = 0$ $\mathbf{a} = \mathbf{a}_0$ $\mathbf{v} = \mathbf{v}_0$	$r = r_0$ $\omega = \omega_0$ $\omega = \frac{d\theta}{dt}$	$\theta = \omega t + \theta_0$ $v = \omega r$ $a = \omega^2 r = \frac{v^2}{r}$ $\mathbf{r} = \mathbf{r} (\mathbf{i} \cos \theta + \mathbf{j} \sin \theta)$ $\mathbf{v} = \mathbf{v} (-\mathbf{j} \sin \theta + \mathbf{i} \cos \theta)$			
Simple Harmonic Motion	$\mathbf{a} = -\mathbf{\omega}^2 \mathbf{r}$ $\mathbf{a} \times \mathbf{v} = 0$	$\mathbf{a} = -\omega^2 x$	$\mathbf{r} = \mathbf{A} \cos (\omega t + \delta)$ $\mathbf{v} = \mathbf{V} \sin (\omega t + \delta)$ $\mathbf{V} = -\omega \mathbf{A}$	$\mathbf{x} = \mathbf{A}\cos(\omega t + \delta)$ $\mathbf{v} = -\omega \mathbf{A}\sin(\omega t + \delta)$	$\mathbf{x} = -\mathbf{A} \qquad \mathbf{x} = 0$ $\mathbf{v} = 0  \mathbf{v} \qquad \mathbf{v}$ $\mathbf{a} \qquad \mathbf{a} \qquad \mathbf{a} = 0$	x = A

Fig. 2. Kinematic models.

particle is a diagram of its trajectory in position space, with *vector* or *scalar labels* for kinematical variables *only*. The vectors indicate velocity, acceleration, and position (as appropriate) at critical and typical times, such as the beginning, end and middle of the trajectory. As Heller and Reif have emphasized,<sup>5</sup> forces do not belong on a motion map, else they get confused with the kinematical variables.

Of course, an accurate motion map cannot usually be drawn until the equations of motion have been solved, so the motion description may have to remain incomplete until then. Just the same, a qualitative description based on the kinematical assumption (actually, law) that motion is continuous is possible in the initial modeling stage.

In an interaction description, each *agent* acting on the object is identified along with the *type* of interaction. Then interaction variables are introduced to represent the interactions, and features of the interaction are described qualitatively using diagramatic techniques. The appropriate technique depends on the model and interaction type. Force diagrams are appropriate when interactions are represented by forces. But energy diagrams are appropriate when interactions are represented by potentials (derived interaction variables). However, in contrast to a force diagram, an energy diagram cannot be drawn until the interaction law has been specified, so it is less useful for an initial description. For pedagogical purposes, interaction maps deserve special emphasis, as Reif and Heller have shown. An *interaction map* describes the forces acting on a particle at key points on its trajectory. It is like a motion map, except *that force diagrams* are drawn at the key points instead of *kinematical diagrams* indicating velocity and acceleration. By comparing an interaction map with the corresponding motion map, students can check for agreement between resultant force and acceleration vectors. This is a valuable check for consistency between their motion and interaction descriptions, as well as an important test of basic understanding.

Introductory textbooks are liberally decorated with diagrams, but they fail to convey to students the *essential* role of diagrams in problem solving or, indeed, to distinguish the roles of different kinds of diagram. It is true that an expert sometimes solves problems without using diagrams, but then the information in a diagram must be given an equivalent representation in the expert's head. Students need to deal with the explicit representation of information in diagrams, because they have not developed the necessary "physical intuition" to get along without them. Indeed, practice in constructing and interpreting diagrams of various kinds probably contributes greatly to the development of physical intuition.

The purpose of a map in modeling is to represent geometrical relations among objects in the model, or kinematic features of a trajectory in a motion map. Labels for geometrical variables like distances, angles, directions, and position coordinates are integral parts of a map, because they specify the physical referents or, if you will, the physical interpretation of symbols that appear in the mathematical equations of the model.

Forces should be represented on a map by arrows with tails attached to the points where the forces act. Unfortunately, introductory physics and engineering textbooks often disregard this important convention. Sometimes they place a force arrowhead at the point of application to indicate a "push" instead of a "pull." This little bit of anthropomorphism only makes it more difficult for students to distinguish their sensory perceptions of contact with objects from the objective physical concept of force. Moreover, to develop a clear conception of a force field, it is essential to associate each force with a particular point at which it acts. This is reason enough to teach students to associate the tail of a force vector with a point of application from the beginning.

To write the equations of motion for a material object, one must conceptually separate the object from its environment. The construction of "freebody diagrams" helps students learn to do this. Such a diagram represents only the forces on a body and the points at which they act. It should be distinguished from a force diagram which represents forces alone. Unfortunately, many textbooks fail to do this. They draw a full free-body diagram for some rigid body such as a block on an inclined plane; then they write down equations for a point particle model of the body, without even mentioning that, in doing so, they have ignored information on the diagram about where the forces act. This is good opportunity to emphasize to students that every model is only a partial representation of an object, sometimes ignoring obvious properties. In this case, the particle model ignores the size and shape of an object, properties which are later taken into account in a more complete rigid body model. Accordingly, when a particle model is employed, the free-body diagram for an extended body should be reduced to a force diagram, the free-body diagram for a particle.

The pedagogical importance of drawing labeled force diagrams can hardly be overestimated. To draw such a diagram, the student must first identify the relevant forces. The labels on the diagram provide a physical interpretation for symbols in the equations of motion. A complete diagram with tails of the force vectors at one point provides the guide a student needs to write down the correct equations of motion. Few students realize the significance of force diagrams unless it is stressed in instruction.

Our discussion of the description stage has been rather long-winded, because this is where students have the most difficulty, yet description is the modeling stage passed over most quickly by textbooks and teachers.

(II) In *The Formulation Stage* of model development, the physical laws of motion and interaction are applied to determine definite equations of motion for the model object and any subsidiary equations of constraint. The passage from force diagrams to equations of motion is by no means automatic. The main point to be understood is that f = ma becomes an equation of motion only when the functional form of f has been specified with one or more specific force laws. Textbooks and instructors have been known to write down equations of motion without helping students identify all the assumptions involved. In particular, there is a tendency to pull equations of constraint "out of a hat." Textbooks usually fail to explain that equations of constraint in mechanics arise from tacit assumptions about internal forces. Students should be alerted to this by analyzing particular examples so they understand that every physical connection in mechanics comes from forces.

(III) In *The Ramification Stage*, the special properties and implications of the model are worked out. The equations of motion are solved to determine trajectories with various initial conditions; the time dependence of derived descriptors such as energy is determined; results are represented analytically and graphically and then analyzed. A ramification which describes the time evolution of some descriptive variable, such as energy, can be regarded as a *process model*. Let us refer to a model object together with one or more of its main ramifications as a *ramified model*.

The ramification process is largely mathematical and textbooks usually treat it adequately, for example, in analyzing simple harmonic motion as a ramification of the abstract model for a particle bound by a linear force. Some general ramification techniques, such as the *method of constraint satisfaction*, are discussed by Reif and Heller.<sup>2</sup> The main deficiency in textbook treatments is that ramifications are not clearly identified as such and integrated with the general modeling process. This contributes to the difficulty students have in recognizing when a particular ramification is called for.

Figure 2 displays ramifications for the principal kinematical models of particle mechanics. The models are specified by defining equations in vectorial or coordinate form. The ramifications include solutions and motion maps as aids to interpret the solutions. Figure 2 is offered here for general use as an instructional aid, displaying the most important things students need to know about ramifications in introductory particle mechanics. I have found it helpful to supply a copy to each student for quick reference when problem solving in class and homework. I recommend that students become thoroughly familiar with the ramified models of each kinematical type in the figure before studying the associated dynamics. Then they should be required to identify the kinematical type in every dynamical model until it becomes automatic. Thus, for example, they should come to recognize that a constant force, whatever its origin, implies uniform acceleration, so they have its ramifications already in Fig. 2. They should

become so familiar with the contents of the figure that the printed copy is unnecessary at exam time.

(IV) *The Validation Stage* is concerned with empirical evaluation of the ramified model. In a textbook problem this may amount to no more than assessing the reasonableness of numerical results. However, in scientific research it may involve an elaborate experimental test.

Students frequently fail to realize when the answer to a textbook problem is unreasonable and have no idea how the answer might be checked. I submit that a major reason for such failure is that the students are only vaguely aware of the model underlying their results. They do not realize that the complete solution to a problem is based on a model from which any numerical answers come as subsidiary results. It is the whole model which needs to be evaluated when a solution is checked. As long as students regard the solution as a mere number or formula, the only way they have to check it is by comparison with an answer key.

The approach I am advocating here is aptly characterized by the slogan THE MODEL IS THE MESSAGE.<sup>6</sup> Students should be taught that the key to solving a typical physics problem is the development of a model from the given information. Indeed, the problem cannot be fully understood until the model has been constructed. Moreover, the information given in a problem is invariably insufficient even for understanding the problem. It must be supplemented by theoretical knowledge to construct a model. Thereafter, the problem solution follows from some ramification of the model. This, I submit, is the core of truth in the old saying "a problem understood is half solved!"

The modeling strategy I have been discussing provides a coherent framework for lectures about models throughout a physics course. I recommend that the instructor explain the relevance to the appropriate modeling stages of everything he discusses. If he doesn't know, he may learn something by thinking about it. He should strive, also, to show students how models are used to "understand" empirical phenomena. In particular, every lecture demonstration or experiment should be accompanied by a clear explication of the model or partial model used to interpret it. THE MODEL IS THE MESSAGE! And it is worthwhile to compare alternative models to show how empirical evidence is used to determine which one is "better." DIFFERENT MODELS, DIFFERENT MESSAGES! Finally, students should be encouraged to employ the modeling strategy in analyzing what they read in the textbook. They should learn to recognize in their reading when THE MODEL IS THE MESSAGE.

For problem solving, our modeling strategy needs to be supplemented by some additional procedural knowledge. Any physics problem can be attacked with the following general *model deployment strategy:* 

(I) *Develop* a suitable model of the situation specified by the problem (if possible).

(II) *Ramify* the model to generate the desired information (if possible). This deployment strategy directs model development toward a specific goal. A physicist possesses a battery of abstract models with ramifications already worked out or easily generated. He solves many problems routinely by simply selecting a ramified model from this battery and matching it to the situation in the problem. For example, once he has identified a problem as a "projectile problem," he is ready immediately to deploy the ramification for uniform acceleration in Fig. 2 to solve it. If necessary, he can readily generate further ramifications, such as a projectile "range formula." For problems like this, the key to model deployment is

simply choosing the right ramified model. For other problems, it is necessary to develop a model from scratch. To implement the general deployment strategy we need some deployment tactics:

- (1) The attack on a problem begins by extracting the information which can be used in model development and representing it in some schematic form. This information is of two types: about objects and their properties or about processes.
- (2) The initial analysis of the problem is completed by formulating the *goal* in terms of information about objects or processes to be determined.
- (3) From the given information about properties one can determine the relevant scientific theory and select model types for the objects of interest. For a problem in mechanics, we can proceed with the model development process outlined in Fig. 1.
- (4) Before generating a model description, one must decide whether to use basic or derived variables. The best decision depends on specialized knowledge about the processes in the problem. For example, we know from experience that momentum variables are most convenient for describing collision processes.
- (5) After a model has been formulated, it should be checked to see if the specified information is theoretically sufficient to determine the desired information. At this point it should also be possible to identify any specified information which is contradictory or irrelevant to the goal.
- (6) To get most quickly to the goal, it is often best to select or derive equations for desired variables from the laws of the model, and then proceed to solve those equations. The main point here is that, in model deployment, ramification is directed toward a specific goal, whereas, in general model development, the purpose of ramification is to explore and survey implications of the model. Such exploration and survey are the main source of the specific information needed to guide model deployment, including decisions as to the best choice of variables in the descriptive stage.

Physicists have learned such modeling strategies and tactics from long experience. The pedagogical question is whether students can learn them more quickly and efficiently when they are explicitly formulated and taught.

Problem solving research shows that for routine problems physicists pass quickly and effortlessly through the descriptive stage of model development. They have mastered the descriptive process so thoroughly that most of it can be carried out mentally with only a few overt manifestations, such as a rapidly drawn diagram. But students frequently fail to complete some part of the descriptive stage and are consequently unable to complete the modeling needed to solve the problem. On the other hand, for complex or "tricky" problems the expert typically spends much more time than the novice on the descriptive stage. The expert does not move on to the formulation stage until a satisfactory description has been achieved. Since description is the first stage in modeling, all this suggests that improved instruction on the descriptive stage in modeling is the most critical step toward improving student understanding and performance. Empirical evidence in support of this surmise will be given in a subsequent paper.

#### **D.** Modeling theory

*Modeling theory* is a general theory of procedural knowledge in science. In the preceding pages modeling theory has been formulated with an eye to specific applications in mechanics. But we are equally interested in developing a general theory of instruction applicable to the teaching of any part of physics. To show that the formation of modeling theory is easily generalized, the model development process is outlined in Fig. 3 as a straightforward generalization of Fig. 1.

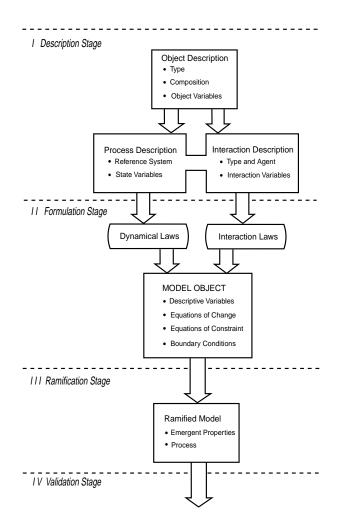


Fig. 3. General model development.

The formulation of model development schematized in Fig. 3 applies not only to every branch of physics, but to every field of science. Modeling theory should be regarded as an adjunct of *Systems Theory*, a general theory of the structure and function of mathematical models which has been under development during the last few decades chiefly by engineers and applied mathematicians. Mario Bunge<sup>7</sup> has developed a System Theory into a general theory of the structure of science. The applicability of modeling theory to every scientific field is evident in his work.

Let us note some distinctive features of Fig. 3, especially in comparison with Fig. 1. The object to be modeled may be a composite object, in other words, a *system* composed of more than one object. Accordingly, a description of its

composition must specify the *type* of each component object as determined by the relevant scientific theory. The motion description of Fig. 1 has been generalized to the concept of process description, but still the state variables represent intrinsic properties of the system which may vary with time. The interaction description includes a description of the *structure* of the system by specifying the internal connections (or interactions) between component objects. The specific relations of the internal interactions to the state variables is determined by the relevant theory. Especially important is the determination of *emergent properties* in the ramification stage. These are distinctive properties of the system as a whole which are not properties of any of its component objects. The determination of emergent properties can be quite difficult for "nonlinear systems."

To be assured that the characterization of model development in Fig. 3 is not impractically vague, let us consider its application to modeling outside the domain of mechanics. Its application to modeling a simple electrical circuit is shown in Fig. 4. Note that classification of the object as an electrical circuit amounts to a decision that electrical circuit theory is the relevant theory to employ in modeling it. Circuit theory specifies the kinds of variables to be employed in a description and tells us that other variables, such as the mass of the object, are irrelevant. Circuit theory has its own system of special modeling techniques, including rules for constructing and interpreting circuit diagrams such as the one in Fig. 4. Note how the diagram relates to the three descriptive substages.

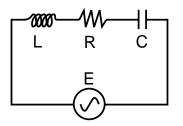


Fig. 4. Modeling an LRC circuit.

I. Description

- Object description. Type: Electric circuit. Composition: Inductor, resistor, capacitor. Object Variables: L, R, C. Α.
- B. Process description (see ramifications). State variables: Current I and capacitor charge Q.
- C. Interaction description. Type and agent: AC generator. Internal connections (among components): see diagram. External connections: some source of Emf. Interaction variable: Emf E.

II. Formulation

- A. Interaction laws: (1)  $E = E_0 \sin \omega t$ . (2) Potentials across components: *LI*, *RI*, *Q*/C. B. Dynamical laws: Kirchhoff's laws.
- C. Abstract model: Equations of change:  $L\dot{I} + RI + Q/C = E$ ,  $I = \dot{Q}$
- III. Ramifications (some examples): Steady-state solution described by phasor diagram. Emergent properties: resonance and tuning.

Circuit theory could be formulated as a self-contained theory for modeling a special class of objects, including applicability and utility conditions for deciding when the theory is relevant. This would facilitate the use of circuit theory in model development and deployment. However, in the typical introductory physics textbook the principles and special techniques of circuit theory are scattered about and never brought together in a systematic and complete formulation. This seems to be due to the fact that circuit theory is not a fundamental theory of physics, so the textbooks are preoccupied with establishing the basis for circuit theory from more fundamental principles such as the laws of Ampere and Faraday. To be sure, the derivation of circuit theory principles is of great importance, because it establishes the limitations as well as the generic origins of those special principles. However, the derivation should be clearly separated from the formulation of circuit theory for theoretical reasons as well as the practical reasons I have already mentioned. Circuit theory provides students with an excellent example of the level structure of science, where the principles for modeling objects at one level are self-contained, but derivable from principles at a more generic level. As Bunge<sup>7</sup> shows, elucidation of the level structure of science is the grand theme of Systems Theory for interrelating all the sciences. Circuit theory also provides striking examples of emergent properties that appear in systems of increasing complexity, in particular the properties of resonance and tuning that appear in ramifications of an LRC circuit.

These observations are meant to suggest that a systematic use of modeling theory in instruction should help students gain a unified and coherent view of science. To be sure, modeling theory stands as much in need of development as of application. And the task is far from trivial, though in large part it will consist of articulating and organizing well-known ideas.

### **III. COGNITIVE SCIENCE AND INSTRUCTIONAL THEORY**

Most physicists pay scant attention to psychology, but they cannot avoid it in their teaching. Instructional practice is necessarily grounded in some system of beliefs about knowing and learning, however tacit or rudimentary. Cognitive psychology is still too immature to provide a secure foundation for instructional theory, but the situation is changing. Recent cognitive research has identified serious flaws in traditional instructional practice and clarified difficult problems that need to be addressed. My purpose here is to call attention to some of this work and its pedagogical implications. This extends and updates the discussion in a previous article,<sup>8</sup> which will be taken for granted as background.

The development of a scientific theory of cognitive processes is too difficult and too important to be left to the psychologists alone. Indeed, it has already evolved into a multidisciplinary research program called *Cognitive Science*.<sup>9</sup> The general aim is to produce a comprehensive *theory of intelligent systems*, including artificial intelligence on one hand and human intelligence on the other. The program thus cuts across every field of intellectual endeavor from computer science to psychology, including the history and philosophy of science as well as linguistics, mathematics, and the various sciences. The processes of learning and understanding physics and mathematics have become a focus of cognitive research, because these subjects are especially clear cut and well developed. I will emphasize such work because of its special relevance to physics teaching. But my main concern is to place the development of instructional theory within the broader program of cognitive science.

#### A. Problem solving and expert systems

The analysis of cognitive processes in problem solving has emerged as a major line of cognitive research in the last two decades.<sup>10</sup> This includes research on solving textbook problems in introductory physics.<sup>11-15</sup> The research has been concerned with identifying and documenting empirical differences between expert

and novice problem solving performance, and developing a plausible theory to account for those differences. Although the expert, of course, possesses much more factual knowledge than the novice, superior problem-solving performance is due mainly to *procedural knowledge* that enables the expert to bring the right facts and principles to bear on a problem at the right time. To identify and describe that procedural knowledge precisely is a difficult problem in cognitive research, for much of it is *tacit knowledge* which is not recognized even by the expert who possesses it. The pedagogical value of such research in any cognitive domain is obvious, for it should help pinpoint precisely what needs to be learned for skilled performance in that domain. Another application is to the design of expert systems. An expert system is a computer program capable of skilled problem-solving performance in some specific domain. Clearly, such a program cannot be written until the necessary procedural knowledge can be precisely described. The development of expert systems for specialized applications, from the daily adjustment of airline fares to medical diagnoses, is expanding rapidly. This will undoubtedly have a major economic and social impact over the next two decades.

In a specified cognitive domain, such as Newtonian mechanics, the procedural knowledge required for problem solving can be described as a system of productions. A *production*<sup>16</sup> is defined as a condition-action pair expressible in the form: *If* condition A is satisfied, *then* perform action B. A good test for the adequacy of a procedural description is using it to write a computer program to emulate the problem solving performance of a human subject. This is often difficult or impossible with current computer systems, because they cannot match human perceptual capabilities for recognizing when conditions are satisfied. Even so, the demanding goal of computer emulation has stimulated researchers to sharpen their descriptions of procedural knowledge and identify gaps therein. The difficulty of the task has made it clear that expert knowledge, even in a "simple" domain like elementary mechanics, is much more complex and extensive than the experts themselves generally realize.

Problem solving research and theory has important implications for physics teaching. To begin with, the fact that experts do not solve problems the way they say that they do has been carefully documented. What the expert says looks like a recital from a standard textbook, but what the expert does is quite different. Sometime ago Einstein noted a similar discrepancy in what theoretical physicists say about the methods they use, and he offered the advice<sup>17</sup>: "Don't listen to their words, fix your attention on their deeds." I believe this attitude is one of the sources of Einstein's genius, for his greatest work came from a critique of physical presuppositions which everyone else overlooked. All this suggests that the typical physics professor is not likely to be very good at teaching problem solving to beginners.

A number of general problem solving strategies, such as "means-end analysis," have been identified and thoroughly studied. A strategy is "general" if it applies to a wide range of cognitive domains. Such strategies are also "weak" in the sense that, by themselves, they support inefficient problem solving methods. Strong strategies and methods employ domain specific knowledge, so they have a limited range of applicability. There has not been much success in formulating strategies of intermediate strength. Thus, most expert systems developed so far are little more than bundles of productions, without significant strategies to organize them. And most problem solving research in physics has recognized only very weak and very strong methods. However, we have seen in Sec. II that modeling theory provides a powerful problem solving strategy with wide applicability in science.

Accordingly, I submit that experts tacitly employ a *model-centered strategy* for solving physics problems. This is to say that the expert typically attacks a physics problem by first constructing an abstract model from the "givens" in the problem and then deploying the model to determine the desired "unknowns." The expert's tactical tricks for problem solving are thus coordinated in a general modeling strategy. In other words, the modeling theory discussed in Part I provides the basis for a detailed *modeling theory of expert problem solving* in physics. It can be expected to give a good account of empirical data on expert problem solving, but we are more concerned here with the way it fits into a general instructional theory.

Problem solving is traditionally taught by providing examples for the student to emulate. The drawback is the students tend to emulate what they see. What they see, typically, is that after a little talk some formulas are written down from which a numerical solution is obtained by manipulation and substitution. The teacher or textbook may say that it is important to do such things as to "draw a diagram," but they seldom say why, and the student can see that the answer comes from a formula, so why bother with a diagram? Little wonder that students come to see selection of the correct formulas as the key to problem solving. Thus, they tend to develop a formula-centered problem solving strategy<sup>15</sup> like the following: (a) search the problem statement for a list of given and unknown variables, (b) search a list of formulas for an equation which involves those variables alone, and (c) solve the equation for the unknown and presto, the solution! This strategy is especially effective for homework problems when the necessary formulas can be found in the chapter from which the problems are assigned. Dedicated students learn this strategy well by working a lot of assigned problems, for they know that "practice makes perfect!" Indeed, they may become quite adept at formula hunting.

The trouble with teaching by example is that so much of the expert's procedural knowledge is invisible to the student. Considering the research required to identify the expert's tacit knowledge, one wonders how such knowledge ever gets transmitted to students under traditional instruction. Perhaps it is not transmitted, and it is only learned by those few students who rediscover it for themselves. At any rate, tacit expert knowledge should be more teachable after it has been given explicit formulation.

Complex procedural knowledge is not easy to teach even when an explicit formulation of the procedures is available. In his studies of mathematical problem solving, Schoenfeld<sup>18</sup> has shown how a student's intellectual performance is profoundly affected by noncognitive beliefs about self, the discipline, the environment and the task at hand. For example, a student who believes that "science is a collection of facts" is likely to approach physics as a fact collector and so be blind to the structure of physics. Students are not easily weaned from a formula-centered problem solving strategy that has been successful in the past. They must be confronted with situations where the formula-centered strategy clearly fails, and recognized that a better strategy is available. To facilitate the transition to a powerful model-centered strategy, the instructor needs a clear understanding of modeling theory and a systematic method for teaching it.

### **B.** Representations of knowledge

There is a temptation to regard computer emulations of human problem solving performance as models of human cognitive processes. It should be realized, therefore, that such models are severely limited and in some ways down-right misleading. Most computer models of human cognition to date suffer two major defects. In the first place, they are incapable of learning outside of mere data accumulation. Their performances can be improved only by programmers who do the learning for them. In the second place, they represent and process information serially, whereas the human brain is undoubtedly a parallel processor. Of course, one reason for this is the fact that available computers are serial processors. But serial models also result from modeling problem solving behavior directly, because behavior is necessarily serial even if the underlying processes that direct it are not. Computer emulation of human perceptual skills like object recognition has proved to be especially difficult, in large part, no doubt, because this is a modeling of parallel processes by a serial computer.

Aside from computer emulations, serial models of cognition have been seriously considered by philosophers and psychologists operating on the premise that language is essential to cognition, for language production appears to be a serial process, on the surface at least. Beginning with George Boole in 1854, analysis of language syntax led to the development of propositional (or symbolic) logic, which has often been regarded as a theory of basic operations underlying cognition. A variant of this idea was proposed by psychologist Jean Piaget, though Piaget held that logic is not a derivative of language, but originates rather in the total coordination of actions.<sup>19</sup> Piaget suggested that a (mathematical) group of four operations, called the INRC group, develops spontaneously in humans as a system of mental operations underlying his "Formal Operational Stage," a level of cognitive development at which mathematical and scientific thinking becomes possible. This bold hypothesis is strong enough to be subjected to empirical test. Unfortunately, the conclusion after careful evaluation is that it fails.<sup>20</sup> Evidently the relation between basic mental operations and logical operations is not so simple. But much of Piaget's theory remains viable, including his characterization of stages in cognitive development.<sup>8</sup>

The idea of using propositional logic to model cognitive processes faces many other difficulties, most notably in explaining what it means to understand a proposition. John-son-Laird has argued persuasively that one understands a proposition about the real world only by constructing a mental model of the situation to which the proposition refers.<sup>21</sup> This idea has far-reaching pedagogical implications, and I propose to take it as a premise of our pedagogical theory. The idea that the development of mental models is crucial to "physical understanding" has been the subject of a number of cognitive studies.<sup>22</sup> However, there is little agreement on what constitutes a mental model.

Modeling theory tells us that a situation in the real world is accounted for "physically" by constructing a mathematical model to represent it. Now we must distinguish two kinds of representation for the model: an *external* (objective) representation in terms of mathematical symbols, maps, diagrams, etc., and an *internal* (mental or subjective) representation in the brain of someone who understands it. In other words, to understand a mathematical model one needs a corresponding mental model. Evidently an ability to construct such mental models is what physicists mean by "physical intuition." Perhaps cognitive development could best be described as development of mental modeling skills. We don't know

much about mental representations, but we do know they are related to external representations, and there is every reason to believe that the development of physical intuition is stimulated by suitable experience with external representations.

Any bit of knowledge can be represented in many different ways. The most appropriate mode of representation depends on how the information is to be used. Specific modes of representation have often played critical roles in scientific discovery. This has been documented by Arthur Miller in his studies of the role of imagery in important discoveries in physics.<sup>23,24</sup> By "imagery" he evidently means some form of mental representation, but his analysis emphasizes the development of external representations for that imagery, such as energy level diagrams and Feynman diagrams.

Surely diagrammatic techniques are as important in pedagogy and understanding as in research and discovery. Yet their pedagogical role has hardly been studied. It is not enough to know what the diagrammatic techniques are. Research is needed to determine what it takes to teach skillful use of the techniques. We know that most students fail to master the use of "free-body diagrams" in introductory physics. Surely, there is greater failure to understand the more complex techniques for representing electric and magnetic fields. Every physicist knows these techniques are essential to understanding the field concept, and textbooks show that great efforts have been expended to teach them. However, these efforts have all been directed toward the techniques themselves, without any study of the difficulties students have in learning them or even what constitutes expert utilization of the techniques.

The upshot of my argument here is that mastery of various modes of external knowledge representation is essential to the development of physical intuition, and substantial pedagogical research is needed to determine how this can be taught efficiently. Although pedagogical research should be able to go along way by systematically studying how external knowledge representations are learned and employed, pedagogical theory should be based ultimately on a theory of internal knowledge representation in the brain. Few people realize that a significant theory of this kind exists already and is developing rapidly. As the theory is not far from the point where it will have pedagogical implications, a brief report on its status may be useful.

Neural network theories of information processing in the brain are based on the "neuron doctrine," which holds that neurons are the basic processing elements. Although the neuron doctrine has not been established beyond doubt, there is considerable evidence in its favor, and no significant alternatives are available. Moreover, there is wide agreement on the modes of neuronal signal transmission, though this is a subject of active research. Stephen Grossberg has developed a neural network theory with a handful of basic mechanisms and principles which accounts for an impressive range of data on perception, learning, memory, attention, motor control, and even emotions.<sup>25,26</sup> According to this theory, the basic representational unit of information in the brain is a spatial pattern. Even temporal information is represented as a spatial pattern. The theory identifies specific neural mechanisms for what psychologists call short-term memory (STM) and long-term memory (LTM). The STM is a mechanism for temporary information storage which allows rapid processing and the selection of information worth storing permanently by the LTM mechanism. The LTM mechanism for permanent information storage and retrieval is also a universal

*learning mechanism.* Every kind of human learning is explained by embedding this single mechanism in a suitable network.

Grossberg has formulated a number of general problems, principles and theorems to guide the design of networks with particular information processing capabilities. A key problem is the design of an *adaptive filter* for encoding significant patterns. The successful solution of this problem explains how the brain spontaneously develops and updates a code for classifying incoming patterns. It tells how to design a *self-organizing* system for extracting invariants from its experience. The same design explains the *unitization process* whereby coherent clusters of coded information are compressed into single units, a process called *chunking* by psychologists. Any adaptive system capable of developing and updating codes for incoming information needs a code protection mechanism to prevent the adventitous encoding of erroneous information. Grossberg calls this the stability-plasticity dilemma: "How can an organism's adaptive mechanisms be stable enough to resist environmental fluctuations which do not alter its behavioral success, but plastic enough to rapidly change in response to environmental demands that do alter its behavioral success." His brilliant solution to this problem has profound implications for learning theory. He maintains that familiar and novel events must be processed differently. To accomplish that, he proposes a system with two complementary subsystems: an *attentional* subsystem for processing familiar (or expected) events and an orienting subsystem activated by unfamiliar (or unexpected) events. The entire system controls the allocation of conscious *attention*, a mechanism for identifying meaningful patterns and storing them in LTM (learning).

These qualitative observations barely skim the surface of Grossberg's theory. I should add that the theory has a mathematical formulation in the tradition of theoretical physics. It is sufficiently well defined to be emulated on computers. Indeed, it provides the theory for the design of new computer systems with real time interactive parallel processing, hence capabilities beyond the reach of serial computers.<sup>27</sup> Such systems are being built even now and promise to take the computer revolution beyond the so-called "fifth generation computers."

#### **C. Dialectics of conceptual change**

There is new substantial evidence that beginning students In physics have prior common sense (mis)conceptions about the physical world which interfere with learning and understanding of the subject (Refs. 3, 4, and references cited therein). These misconceptions are very *stable* in the sense that conventional instruction is ineffective in correcting them. Moreover, it appears that some serious misconceptions about physics are inadvertently promoted by instruction; for example, the formula-centered approach to problem solving. To design efficient instruction we need to account for the stability of these misconceptions and the conditions necessary and sufficient to correct them. There is precious little pedagogical research bearing directly on this issue. My purpose here is to set forth an intellectual perspective for such research.

The first thing to realize is the stability of misconceptions about physics is not a sign of stupidity among students. On the contrary, it is a consequence of the resistance to conceptual change which every intelligent system must possess to escape the horns of the stability-plasticity dilemma. It is a sign that the necessary conditions for conceptual change have not been met. What are those conditions? Plaget's theory of cognitive development suggests an answer. According to Piaget, cognition has a *figurative* aspect and an *operative* aspect.<sup>19</sup> The figurative aspect concerns the representation of information in static configurations (or states). The operative aspect concerns operations which transform one state to another. These operations are integrated into systems or "mental structures," *called schemata*, which are used to interpret and respond to environmental input. He holds that "the central problem of (cognitive) development is to understand the formation, elaboration, organization, and functioning of these structures." Grossberg goes well beyond Piaget in identifying the configurations as spatial patterns of a definite type and characterizing the basic operations on these patterns as well as mechanisms for performing the operations and organizing them into schemata.

Following biological theory, Piaget suggests that there are two kinds of learning, which he calls assimilation and accommodation. Assimilation is the integration of information into an existing schema. Accommodation is the modification of a schema to be consistent with new information. Under appropriate conditions schema change occurs spontaneously by a process called *equilibration* or *self-regulation*, which involves a feedback loop relating an action to its consequences. Here again Grossberg has gone well beyond Piaget in investigating the design of neural mechanisms capable of both kinds of learning. These include the attentional and orienting subsystems mentioned earlier. It appears that Piaget's "assimilation" can be identified with processing by the attentional subsystem. This can be regarded as an encoding of information into an existing code, while "accommodation" involves the formation of new codes. Actually, in the neural theory any encoding of information produces subtle changes in the code. Grossberg<sup>28</sup> argues that "learners are minimal adaptive predictors who change their internal representations of external events when behavior based upon these representations generates unexpected environmental feedback." This supports "an epistemological framework wherein each observer can possess idiosyncratic and personal definitions of objects or events, and these definitions are refined only when they are maladaptive."

The same general principles of adaptive self-organization within an individual can be seen operating in the scientific community. Historian Thomas Kuhn distinguishes between the processes of "normal science" and "revolutionary science" which are analogous to the processes of assimilation and accommodation.<sup>29</sup> In a scientific revolution the conceptual structure of science is revised. Resistance to scientific revolution must be strong to insure the stability of science against faddish fluctuations in opinion. Revolutionary ideas are never incorporated in the framework of science until they have been thoroughly tested in competition with alternatives. On closer examination, a distinction between the processes of normal and revolutionary science is difficult to make.<sup>30</sup> Thus, in normal science the accommodation process is continually operating to reconcile discrepancies between scientific models and empirical data.

The process by which new ideas about the real world are tested, accepted and integrated into a conceptual framework is of such importance that it deserves a name. I propose to call it a *dialectical process*. The term "dialectical" has unfortunate connotations today, but it calls to mind the rich and controversial history of the underlying idea. Dialectics is about controversy and its resolution by rational means, the engine of conceptual change in every intellectual domain. The essence of the dialectical process is a competition between incompatible ideas, within the context of some conceptual framework, to achieve a resolution called "truth." The competition in science follows fairly definite rules, though a coherent account of the rules cannot be found in any physics textbook. These rules, in fact, can be regarded as rules of inference, so let me speak of *dialectical inference* in science instead of a dialectical process. A coherent, though incomplete, theory of dialectical inference has been put together by Edwin Jaynes and successfully applied to a great range of problems in physics and engineering.<sup>31</sup> It should have a central place in the science curriculum. But the main point of interest here is that dialectical inference is an extension, or perhaps a reflection, of the self-regulation process in human cognition. The main function of this process, within the individual or the entire scientific community, is to produce an optimal representation of the real world consistent with presently available information and prior knowledge.

A scientific revolution is a revolution in the conceptual framework of individual scientists. For beginning students the transition from a common sense conceptual framework to the Newtonian framework is a revolution of comparable magnitude. Indeed, it corresponds to one of the great scientific revolutions. From this perspective, there is no wonder that students have difficulty making the transition. However, the same perspective suggests that the transition can be made only by a dialectical process. So we should be able to use what we know about the dialectical process to design an instructional strategy to promote it. Let me call that a *dialectical teaching strategy*.

A dialectical teaching strategy is appropriate when the student has prior concepts (schemata) which are incompatible with concepts to be taught. The strategy is to provoke in the student a state of "*cognitive conflict*" between the new and prior concepts and induce the student to resolve the conflict by rational means. Hopefully, then, the desired transition will occur because the student recognizes deficiencies in the prior concepts and merit in the new.

Before a dialectical teaching strategy can be implemented, something must be known about the initial conceptual state of the student. The more that is known, the more effective the implementation is likely to be. Unfortunately, such knowledge is not easy to obtain. It is stored in the student's schemata, which are not open to direct inspection by the instructor. The common sense physical intuition of a student entering a first course in physics was developed from long personal experience, mostly without conscious effort. Traditional physics instruction does not adequately take the intuitions of students into account, so it frequently fails to establish the conditions of cognitive conflict needed to drive a transition from common sense intuition to the more veridical intuition of a physicist.

To design instruction that takes the intuitions of individual students into account, one needs to know something about the structure and composition of physical intuition. A "physical" schema is a kind of unarticulated belief which can be observed only indirectly in the behavior patterns of an individual. Nevertheless, schemata can be studied, classified, and represented (partially, at least) as verbally formulated beliefs. This has been done with some success for common sense intuitions about motion and its causes.<sup>4</sup> Fortunately, the physical intuitions of untutored individuals are not totally idiosyncratic. Rather, common sense beliefs (schemata) fall into a small number of fairly well-defined categories. Therefore, practical instruction can be designed to deal with these categories of common sense beliefs without worrying about the idiosyncrasies of individual students.

An individual's schemata (beliefs) are interrelated, so good instructional design should take this into account whenever possible. Physical intuition can be regarded as a *system* of unarticulated beliefs. Research shows that the common sense beliefs of most individuals are only weakly interrelated and frequently inconsistent.<sup>4</sup> In contrast, the beliefs of a physicists are strongly interrelated and highly consistent. This suggests that beliefs of a physicist may be more resistant to change (as in a scientific revolution) than the beliefs of a student.

To provoke cognitive conflict and direct equilibration toward an internally consistent system of beliefs in full accord with experience, that is, a scientific belief system, I recommend a dialectical teaching strategy with the following elements:

- (1) *Explicit formulation*. Students should be engaged in considering systems of explicitly formulated common sense beliefs (not necessarily their own). Usually, the instructor will have to supply the formulation, though it is desirable to have students contribute whenever possible. Research on common sense beliefs makes it possible to do this systematically.
- (2) *Check for external validity.* Students should be induced to check the beliefs for consistency with empirical evidence.
- (3) *Check for internal consistency*. Students should be induced to check for mutual consistency among beliefs.
- (4) *Comparison with alternative beliefs.* Students should be induced to compare and decide between conflicting beliefs and beliefs systems, including, of course, relevant scientific beliefs.

The dialectical teaching strategy can be implemented in a variety of different teaching methods which should be carefully evaluated for effectiveness. Some success using this strategy in a method for teaching problem solving is reported in a subsequent article.<sup>32</sup> Minstrell reports impressive success in teaching the Newtonian force concept to high school students<sup>33</sup>; if his results can be replicated and extended, then we will have convincing empirical evidence that suitable instruction can transform most students into Newtonian thinkers. I should mention that others have argued for teaching methods to promote cognitive conflict.<sup>34</sup> Of course, the venerable *Socratic method* employs a dialectical strategy, and the *Socratic dialog*<sup>35</sup> is a proven means for provoking cognitive conflict. However, the strategy proposed here is more systematic and goal directed than the usual open-ended Socratic method.

Dialectical teaching methods are slow and ponderous, though they can be exciting and effective when skillfully employed. Fortunately, our theory tells us for what purpose dialectical methods are most appropriate, namely, to root out deep-seated and unarticulated beliefs for critical evaluation. For other instructional purposes didactical methods are certainly more efficient and possibly more effective.

The objective of dialectical teaching should be much more than alteration of deep-seated beliefs. It should aim to teach objective procedures and criteria for evaluating beliefs. Students should learn to recognize the flaws in common sense beliefs and justify their own beliefs. They should learn the value of explicit and precise formulations, the need for careful empirical tests, and the processes of objective evaluation. In short, dialectical science teaching should aim to teach *rational (scientific) methods* for evaluating beliefs about the physical world.

# IV. CONCLUSION AND RECOMMENDATIONS FOR RESEARCH

The main contention of this article is that *mathematical modeling should be the central theme of physics instruction*. This means that the teaching of physical facts and theories should be subsidiary to teaching the principles and techniques of mathematical modeling. It calls for a severe reorganization of priorities in physics teaching which can be justified on strong epistemological and psychological grounds.

Since modeling theory is concerned with procedural knowledge, it is best learned in a context of specific modeling activities, where the theory is developed gradually to monitor and guide those activities. I call this a *model-centered instructional strategy*. Active modeling requires the coordination and integration of facts with scientific theory, rather than a mere passive collection of facts and formulas. Modeling principles organize the information in a scientific theory for application to concrete physical situations and problems. Therefore, modelcentered instruction should be an efficient means for teaching the organization of scientific knowledge. Moreover, such instruction focuses on the construction and deployment of well-defined models of physical objects and processes. A *model* object is a conceptual representation of a real thing which behaves in accordance with physical laws. Thus, model-centered instruction focuses on conceptual reconstructions of physical reality. It should be expected, therefore, to be effective in developing the physical intuition of students.

Although some encouraging empirical evidence is available, the best justification for model-centered instruction comes from an analysis of the scientific enterprise. Science has developed rapidly by emulating Newtonian mechanics. I submit that the success of this emulation derives from a transfer to other domains of the general modeling principles imbedded in Newtonian science. Modeling theory is an extraction and analysis of these principles, producing a formulation of modeling strategy and tactics applicable to all the sciences. Instruction in modeling theory is, therefore, instruction in the unity of science and scientific method. But modeling theory is also concerned with domain-specific modeling techniques. The modeling techniques we teach should exemplify good scientific practice, to minimize the artificiality of textbook exercises and maximize transferability to genuine scientific research.

Substantial pedagogical research and development will be required to implement effective model-centered instruction. A formulation of domain-specific modeling techniques sufficient for instructional purposes has been completed only for Newtonian mechanics. And this is the only domain for which a fairly complete profile of student misconceptions is available. But effective methods of instruction which make optimal use of this information remain to be developed. Although we have good reason to believe that basic misconceptions can be eliminated with dialectical methods, this has yet to be demonstrated in practice. Although modeling theory should be helpful in the design of instruction, how much of the theory should be explicitly taught to students remains to be determined. Also, the efficient control of problem solving instruction a "modeltheoretic" analysis of all assigned problems may be necessary. Finally, it will probably be necessary to integrate modeling theory into an introductory textbook on mechanics.

Newtonian mechanics should certainly be the domain where the instructional theory is strenuously tested to see how effective physics teaching can be. Application of modeling theory to other physical domains is a nontrivial task

requiring a high order of scientific insight. I submit, for example, that the archaic formulation of thermodynamics in current textbooks would be substantially modified by a thoroughgoing analysis from the perspective of modeling theory. In every physical domain there is need for analysis of domain specific modeling techniques, including diagramatic techniques of concept representation, to determine how they can be used most effectively in instruction and perhaps even improved.

Unfortunately, the prospects for pedagogical research in physics are bleak, because adequate support by the physics community is lacking. There is no shortage of young people who would like to become engaged in such research, but the opportunities are almost nonexistent. Only a handful of U. S. physics departments have allowed people to complete doctorates in the subject. And most of these people soon turned to something else, as they learned there would be no rewards in academia for continuing their research. Indeed, even a tenured physics professor is more likely to be penalized than rewarded for pedagogical research.

No wonder that most pedagogical research is of such poor quality! In any field it is extremely difficult for an isolated individual to carry out significant research. A productive research program requires a community of active investigators. Efforts to establish a meaningful program of research in science education have been repeatedly squelched by the scientists at the national as well as the departmental level. When science education is forced to compete with scientific research for the budget pie, it is invariably left with the crumbs. The National Science Foundation had to be forced by Congress to allocate significant funds to science education research. It took more than a decade and the vigorous advocacy of Robert Karplus for the NSF Science Education directorate to assemble the necessary expertise and develop programs promoting meaningful research. All this was destroyed overnight when the Reagan administration came to power.

As awareness of a national crisis in science education has increased recently, substantial federal funds have been allocated to cope with the crises on the secondary level. However, little of this is directed toward significant pedagogical research, and much of it promotes a reactionary "back-to-basics" approach. I am not alone in the dour prediction that the main result of this movement will be more bad science teaching and in the opinion that substantial pedagogical research will be essential to a more salutary outcome.<sup>36,37</sup>

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